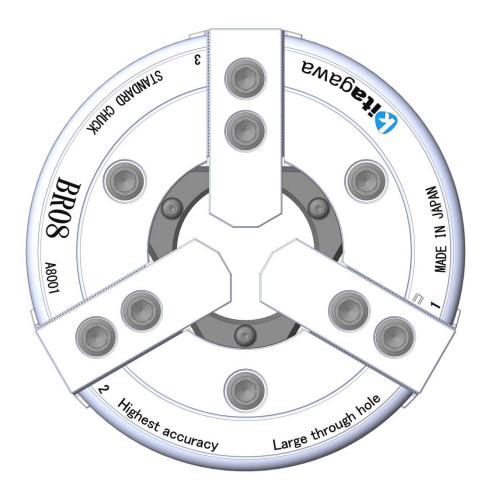


Standard Chuck



Kitagawa Corporation

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Before using this product, be sure to read this manual carefully to understand how to use it correctly.

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1. Preface

1.1. How to Use This Manual

- This manual provides detailed information on this product so that you can understand its performance and functions and use it safely and correctly. Before using this product, be sure to read this manual carefully to understand how to use it correctly.
- This manual has been prepared for intended use for persons in charge of installation, operation, inspection, and maintenance of this product. When the beginners use this product, be sure to receive the guidance from skilled persons, sales agents, or us in advance.
- Store this manual with care in the specified place at hand, and reread it as necessary for correct use of the product.
- This manual is a part of the product. Do not sell or transfer the product to a third party without attaching this manual.
- Read the section "Important Safety Precautions" at the beginning of this manual especially carefully, which summarizes precautions that particularly you should know or follow.
- Failure to follow the instructions and warnings in this manual could result in serious human accidents. Kitagawa shall not be held liable for human accidents, death, damage, or loss that occurred due to a failure to follow this manual.
- This manual does not predict all potential hazards in installation, operation, maintenance, and inspection under all environmental conditions. Therefore, the matters, unless otherwise mentioned clearly as "can be done" or "may be done" in this manual, should be considered as "cannot be done" or "must not be done".
- Please contact us or our agents if you have an uncertainty about safety when you try to perform installation, operation, inspection, or maintenance of the product.
- The information and product specifications described in this manual are subject to change without notice for the purpose of improvement.

1.2. Signal Word Definition



The triangle shown on the left indicates warning. The warning signs are used to alert you to potential safety hazards. To avoid death or injuries that could occur, follow all the instructions given with the warning signs.

Handling precautions that are considered especially important are classified and indicated as shown below according to the degree of risk that could result.

<u> A</u> Danger	Failure to follow the safety precautions below will result in death or serious injuries.
Warning	Failure to follow the safety precautions below could result in death or serious injuries.
	Failure to follow the safety precautions below may result in minor or moderate injuries.
Notice	Indicates instructions which, if you do not heed given instructions, could result in damage to the product or shortened service life, or damage to peripheral equipment.

The signs are classified and indicated as follows according to the type of risk.













General warning

Fire warning

ng l

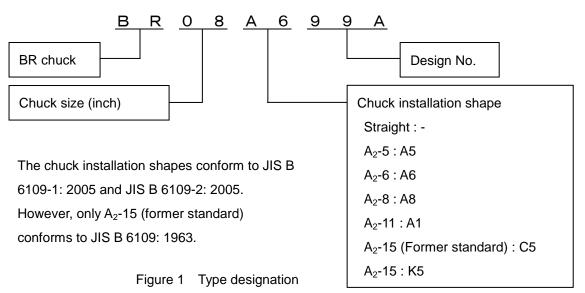
Fly-out warning

High temperature warning

Rotating part warning

Instruction

1.3. Type Designation



1.4. Application Purpose of This Product

The power chuck is installed on machine tools such as NC lathes and machining centres to fix a workpiece. The power chuck is equipped with the jaws to fix the workpiece and they are opened and closed by means of a rotary cylinder. For any other applications, please contact us.

1.5. Unacceptable Application Example

The power chuck is not designed for the applications mentioned below for example.

- To fix an object to be pressed, punched, welded or fused
- To use as a tool holder
- To suspend or transfer an object
- To fix another chuck that grips a workpiece

1.6. Structural Drawing

The power chuck and rotary hydraulic cylinder are respectively installed on both side of the machine spindle and connected with the draw pipe.

The hydraulic pressure applied to the cylinder is converted to thrust that pulls the draw pipe and operates the wedge plunger backward via the draw pipe. Then the master jaw is operated inwardly by the wedge hook and the force is transferred to the top jaw.

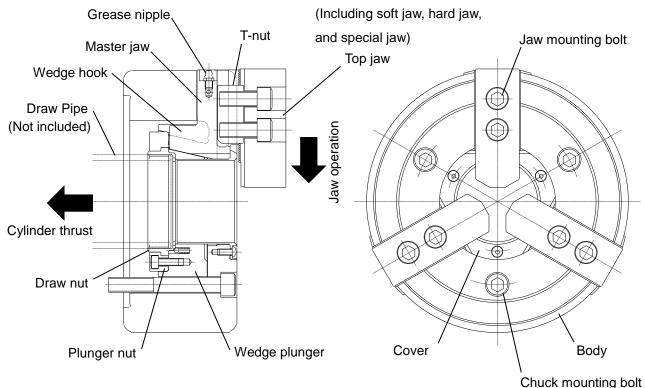


Figure 2 Structural drawing

1.7. Product Range

• This is the chuck instruction manual.

For the cylinder and other peripheral devices, refer to their respective instruction manuals.

1.8. Warranty

The product is warranted for one year after the date of delivery. However, the following cases will void the warranty.

- When parts other than Kitagawa's genuine parts are used.
- When proper maintenance and inspection such as periodic greasing are not performed.
- Other than above, when the product is used in methods not following this manual.

1.9. Parts List

All parts used including consumables shall be genuine parts delivered by Kitagawa.

Kitagawa shall not be held liable for human accidents, death, damage, or loss that occurred due to the use of non-genuine parts.

No.	Parts name	Quantity	No.	Parts name	Quantity
1	Body	1	9	Coil spring	1
2	Wedge plunger	1	10	Plate wrench for draw nut *2	1
3	Master jaw	3	11	Chuck mounting bolt	3
4	Soft jaw *1	3	12	Jaw mounting bolt *1	6
5	T-nut *1	3	13	Plunger nut mounting bolt	9 / 12
6	Plunger nut	1	14	Cover mounting bolt	3
7	Draw nut	1	15	Steel ball	1
8	Cover	1	16	Grease nipple	3

Table 1 Standard delivery range

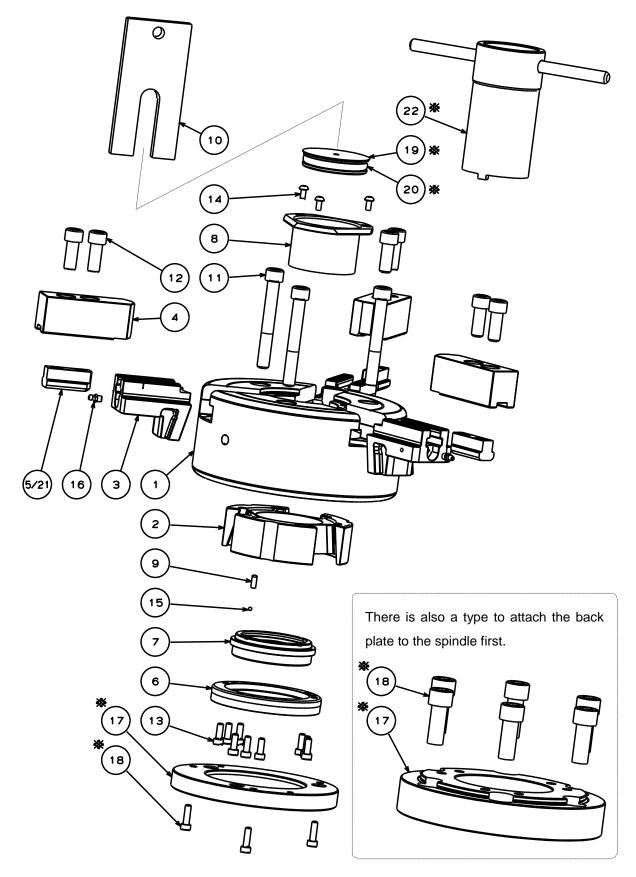
Table 2 Optional parts

No.	Parts name	Quantity	No.	Parts name	Quantity
17	Back plate	1	20	O-ring	1
18	Back plate mounting bolt	3/6/9	21	Tnut-Plus *1	3
19	Сар	1	22	Handle wrench for draw nut *3	1

*1 : Consumables

*2 : Accessory tool

*3 : This is the same tool that comes with the BB200 series, the conventional model. It is compatible with the plate wrench for draw nut [10], so you can choose the one you want.



X : Optional parts

Figure 3 Parts



2. Important Safety Precautions

This chapter summarizes precautions that particularly you should know or follow.

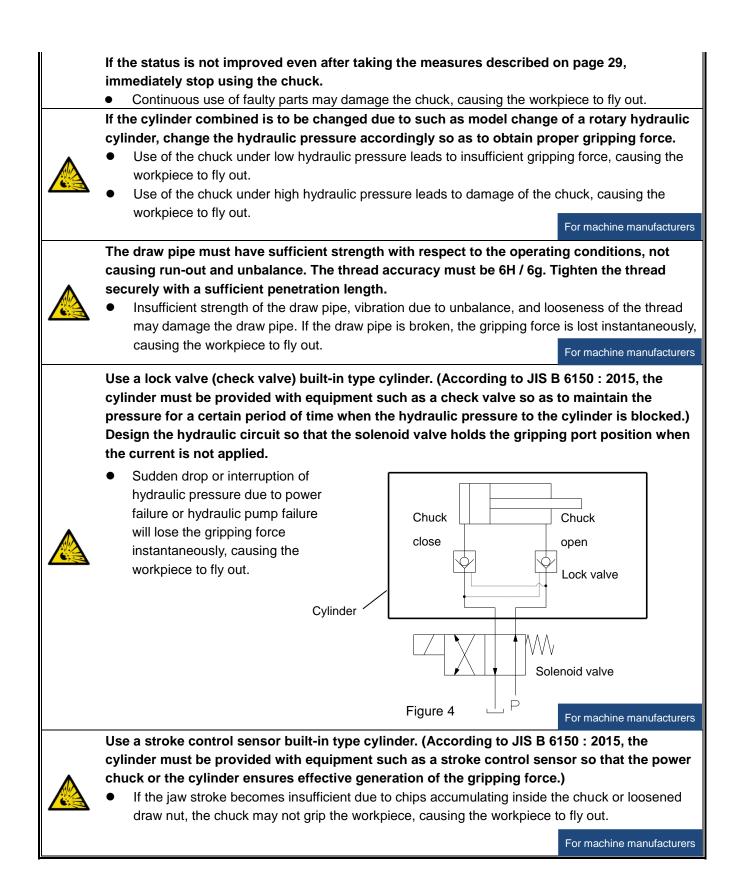
Please read them before starting to use the product.

<u>∧</u> Da	anger Failure to follow the safety precautions below will result in death or serious injuries.							
	Turn off the main power supply of the machine when installing, inspecting, greasing, or							
	replacing the chuck.							
	 The chuck may rotate unexpectedly and entangle your body or clothing. 							
	Do not rotate the spindle with the door open.							
	Provide an interlock to allow spindle rotation only when the door is closed.							
\square	• If the door is not closed, the rotating chuck may entangle your body or clothing or cause the							
	workpiece to fly out.							
	Do not turn OFF the hydraulic pump or operate the solenoid valve during spindle rotation.							
	Before performing workpiece transfer during spindle rotation on an opposed 2-spindle lathe,							
	confirm the machine manufacturer that the operation can be performed safely.							
	• Operating the solenoid valve during spindle rotation will drop or block the hydraulic pressure,							
	causing the gripping force to drop suddenly and the workpiece to fly out.							
	The rotational speed and input force must not exceed the limit in operation. (Refer to "3.							
	Technical Data")							
	 Excessive rotational speed may cause the workpiece to fly out. 							
	 Excessive input force may damage the chuck, causing the workpiece to fly out. 							
	Only the machine manufacturer or the user is to determine cutting conditions, gripping force,							
	and rotational speed according to test cutting result. Adjust the hydraulic pressure so as to							
	obtain the gripping force necessary for machining, and confirm that the necessary gripping							
	force is obtained before starting machining.							
	 Insufficient gripping force may cause the workpiece to fly out. 							
	If you use a top jaw higher or heavier than the standard top jaw, determine the operating							
	condition according to "3.2. Calculation of Operating Condition" on page 13.							
	 Using a top jaw under excessive operating conditions may damage the chuck, causing the 							
	workpiece to fly out.							
	For internal gripping, use the chuck with 1/2 or less of the max. permissible input force for							
	external gripping.							
	 Excessive input force may damage the chuck, causing the workpiece to fly out. 							
	When using fixed jaws instead of one or two top jaws, the input force must be 2/3 or less or							
	1/3 or less of the max. permissible input force.							
	• Since the input force that is normally applied to three jaws evenly is concentrated in two or one							
	jaw, the chuck may be damaged, causing the workpiece to fly out.							
	The gripping diameter must be equal to or less than the body outside diameter.							
	• Using the chuck with the gripping diameter exceeding the body outside diameter may damage							
	the chuck, causing the workpiece to fly out.							
	When machining a workpiece with a long protrusion, support it with the steady rest or the							
	tailstock.							
	 If not, the workpiece may turn at the end, causing the workpiece to fly out. 							

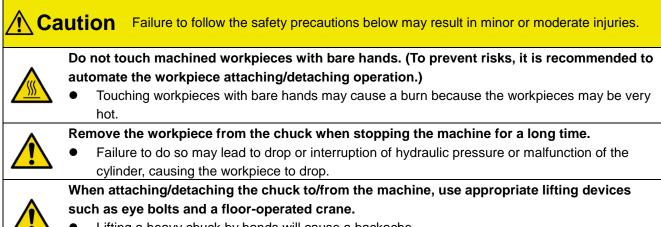
	Do not grip a v	vorknie	o with	slono cl	hance of	r tanara	d ebana		26.2.000	•		
	 Otherwise, 	•		•	•	•	•	อ อนเก เ	as a cas	DL.		
	If a workpiece	or jig ca	auses a	n unbala	ance, re	duce the	e rotatio	nal spe	ed or co	orrect th	ne state	by
	mounting a ba	lance w	eight. T	he reco	mmend	ed balar	nce qua	lity is G	6.3 or le	ss in JI	S B	
	 O905:1992. An unbalanced workpiece generates centrifugal force, causing the workpiece to fly out. 											
	 Vibration generated by the unbalance may damage the chuck, causing the workpiece to fly out. 											
	Confirm that the					-			-			
	rotational spee			-	-	·						
	 A large imp chuck or w 				kpiece b	y interfe	rence ma	ay dama	ige the c	huck, ca	ausing th	е
	If an impact is				ov interf	erence	between	the chu	uck/wor	kpiece a	and the	
	cutter/turret du	-			-					-		
	thoroughly che		_			-	-		g and c	leaning	them a	nd
	perform repair	-						•		مائد م		
	 The impac damage th 	-		-		-		nuous us	se or rau	ity parts	тау	
	Use the chuck							itagawa	۱.			
	If you must us	-					-	-		r compa	any,	
	confirm Kitaga		-							•		e.
	Depending				-	ular cylii	nder, the	chuck a	and the c	cylinder r	may be	
	damaged, Be sure to tigh	-				dtorque	listadi	n Tabla	2 1 and	Table 2	2	
	Use a proper to				-	-			S-1 anu	Table J	-2.	
•	Use only the b				-		-					
	Rotating th	e chuck	with the	iaw mo	unting be	olts loos	ened ma	y cause	the jaw	s and wo	orkpiece	to
	fly out.					_						_
	 If insufficie may be date 				-	-		-	orque is i	Imprope	r, the bol	ts
	may be da	•	-			•	-					
Th	read size	M5	M6	M8	ue for he M10	M12	M14	M16	w M20	M22	M24]
	ng torque [N·m]	7.5	13	33	73	107	171	250	402	539	666	
	n classification: N							200	102	000	000	1
g				,		9						
		Table 3-2	2 Specifi	ed torqu	e for he	k. socket	t button l	nead scr	ew			
Th	read size	M3	M4	M5	M6	M8	M10	M12	M16			
Tightenin	ng torque [N·m]	1.4	3.2	6.4	10.8	26.3	52.1	90.9	224]		
•	Prevent your h	ands ar	nd finge	rs from	being c	aught w	hen grip	oping a	workpie	ce with	the chu	ck.
	(To prevent ris	ks, it is	recomn	nended	to autor	nate the	e workpi	iece atta	aching/c	letachin	g	
<u> </u>	operation.)Otherwise,	vourba	nde and	fingers	mayba	crushed	or cut of	H				
	If any of the ab			-					eration.	it mav b	e a sigr	۱ of
	damage of the						eure uu				e u e.g.	
	✓ The w	orkpiece	slips.			\checkmark	Chatt	ering oco	curs.			
		-	-		ne worse.	. ✓	Mach	ine vibra	tion has	been ind	creased.	
	 Chuck gripping force is reduced. (Cripping force is not increased even by increasing bydraulic pressure) 											

(Gripping force is not increased even by increasing hydraulic pressure.)

ļ



<u>/</u> Wa	rning Failure to follow the safety precautions below could result in death or serious injuries.
Á	 Perform additional machining of tapped holes and pin holes on the chuck only within the allowable range.(Refer to page 26.) Additional machining performed out of the allowable range may damage the chuck, causing the workpiece to fly out. Especially, additional machining to the master jaws and T-nut directly causes fly-out of the workpiece.
	 Supply grease every day. When supplying grease, turn OFF the machine main power and be sure to use the specified grease. (Refer to page 27.) Insufficient greasing or use of grease other than the specified one may drop the gripping force, causing the workpiece to fly out.
	 Disassemble and clean the chuck every six months or 100,000 strokes (cast machining: every two months). (Refer to page 28.) Omitting the disassembly and cleaning and use of the chuck with chips and coolant remaining inside the chuck will lead to insufficient stroke and gripping force drop, causing the workpiece to fly out.
	 Remove the eye bolts and wrench from the chuck after use. Rotating the chuck without removing the eye bolts and wrench may cause them to fly out.
	 Use rustproof coolant. Otherwise, rust that will be formed inside the chuck may drop the gripping force, causing the workpiece to fly out.
	 When stopping the machine for a long time or when storing the chuck without using it for a long period, supply grease and rustproof them beforehand. Otherwise, rust that will be formed inside the chuck may drop the gripping force, causing the workpiece to fly out.
	 Do not wear clothing or accessories such as gloves and necktie which are easy to be caught in. Otherwise, your body or clothing may be entangled.
	 Do not perform the work after drinking alcohol or taking medicine. Impaired judgment or operation mistake may cause serious hazards.



- Lifting a heavy chuck by hands will cause a backache.
- Slipping and dropping the chuck from hands may result in a bruise.

3. Technical Data

3.1. Specifications

Туре			BR06	BR08	BR10	BR12
Plunger stroke mm			12	16	19	23
Jaw	v stroke (in diameter)	mm	5.5	7.4	8.8	10.6
Max	k. permissible speed	min ⁻¹	6000	5000	4500	3500
Thr	ough hole diameter	mm	53	66	81	106
	Max. permissible input force	kN	23	35	49	60
Ext	Max. static gripping force	kN	58.5	90	123	156
External gripping	Max. permissible hydraulic pressure	MPa	2.3 (SR1453)	3.2 (SR1566)	3.4 (SR1781)	3.4 (SR2010)
gripp	(operating cylinder) *1	IVIFa	2.1 (SS1453K)	2.5 (SS1666K)	3.1 (SS1881K)	3.0 (SS2110K)
ing	Dynamic gripping force at max. speed	kN	22.5	36	44	53
	Gripping range	mm	φ16~170	φ22~210	φ31~254	Ф44~315
Int	Max. permissible input force	kN	11.5	17.5	24.5	30
Internal gripping	Max. static gripping force	kN	29.3	45	61.5	78
gripp	Max. permissible hydraulic pressure	MPa	1.2 (SR1453)	1.6 (SR1566)	1.7 (SR1781)	1.7 (SR2010)
ing	(operating cylinder) *1	IVIFa	1.1 (SS1453K)	1.3 (SS1666K)	1.6 (SS1881K)	1.6 (SS2110K)
Mas	ss *2	kg	12.8	22.2	35.8	57.0
Mor	ment of inertia *3	kg∙m²	0.052	0.14	0.32	0.80
Sta	ndard soft jaw type		SJ06B1	SJ08B1	SJ10B1	SJ12N1
Tnu	t-Plus type (option)		TN06PLUS	TN08PLUS	TN10PLUS	TN12PLUS
Bala	ance quality of chuck body *4	JIS B 0905 : 1992 G6.3				
Sto	rage temperature / operating temperat	ture *5		-20∼+50°C	/ -10 ~ +40°C	

Table 4-1 Specification table

*1 : The max. permissible hydraulic pressure differs depending on the cylinder used.

Set the hydraulic pressure according to the cylinder type.

- *2 : The mass is a value when the standard soft jaws and chuck mounting bolts are included.
- *3 : The moment of inertia is obtained by including the standard soft jaws and chuck mounting bolts.
 Here, the soft jaws are mounted to the position protruding outward from the master jaws by a half pitch at the center of the jaw stroke.
- *4 : The balance quality of the chuck body is a value when the soft jaws, T-nut, and jaw mounting bolts are not included.
- *5 : When storing the product, it should be subjected to the antirust treatment and stored in a place free from wetting, condensation, or freeze.

Table 4-2 Specification table (when optional small-diameter gripping soft jaws are used)

Туре	BR08
Small-diameter gripping soft jaw	SJ08S1
Gripping range in external gripping mm	φ12~210

The max. static gripping force in the specifications is the value to be obtained under the following conditions.

- At the max. permissible input force
- Kitagawa's standard soft jaws are used.
- The soft jaw mounting bolts are tightened to the specified torque. (Refer to page 8.)
- The gripping meter is gripped at the center of the jaw stroke. Here, the soft jaws are attached to the position where the soft jaw circumference side end face and the chuck circumference are almost aligned.
- The gripping force is measured by the Kitagawa's gripping meter, and the height of the gripping position is as shown in Figure 5. (Also refer to Table 5)
- The specified grease is used. (Refer to page 27.)
- A variable capacity type pump having a delivery capacity of 20 L/min or more is used as the hydraulic pressure source.
- The pressure is set by the regulator of the pump or that separately provided.

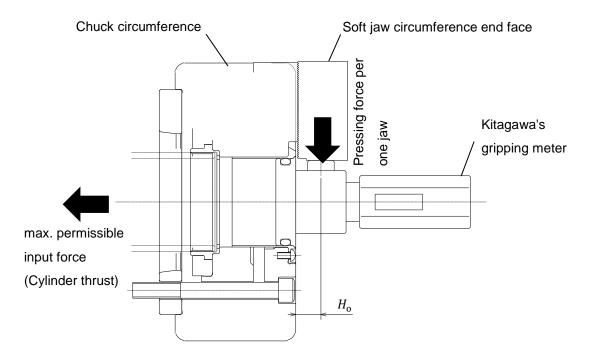


Figure 5 Gripping force measuring method

* The gripping meter indicates the pressing force per one jaw. The gripping force is the total of the pressing forces of all jaws.

3.2. Calculation of Operating Condition

 Table 5
 Symbols for calculation and the meanings

Symbol	Meanir	Meaning				BR10	BR12
H _o	Gripping center height	in specifications	mm	19	21	23	27
H	Gripping center height	mm	-	-	-	-	
H _T	Top surface height of s	tandard soft jaw	mm	33	39	43	52
H _{max}	Gripping part center lin (recommended value)	nit height	mm	60	70	80	90
F	Max. static gripping	External gripping	kN	58.5	90	123	156
F _{g max}	force	Internal gripping	kN	29.3	45	61.5	78
F _{gH}	Static gripping force wi permissible input force		kN	-	-	-	-
Fg	Static gripping force in operation			-	-	-	-
$F_{\rm gD}$	Dynamic gripping force in operation			-	-	-	-
	Max. permissible input	External gripping	kN	23	35	49	60
Q_{\max}	force	Internal gripping	kN	11.5	17.5	24.5	30
Q	Input force in operation	kN	-	-	-	-	
mo	Mass of one standard	kg	0.424	0.782	1.20	1.782	
т	Mass of one top jaw used		kg	-	-	-	-
r _o	Gravity radius of stand	ard soft jaw	mm	48.0	56.7	71.3	98.4
r	Gravity radius of top ja	w used	mm	-	-	-	-
Ζ	Number of jaws			3	3	3	3
n _{max}	Max. permissible spee	d	min ⁻¹	6000	5000	4500	3500
n	Rotational speed in op	eration	min ⁻¹	-	-	-	-
F _{c max}	Loss of gripping force at max. permissible speed		kN	36	54	79	103
F _c	Loss of gripping force at rotational speed during operation			-	-	-	-
ΔF _c	Loss of gripping force of mass increase	kN	-	-	-	-	
Α		ach tura		231	349	377	473
В	Coefficient specific to e	ach type		21	24	25	27

3.2.1. Calculation of Static Gripping Force at Gripping Center Height H

The gripping center height is the distance from the mechanical center point of the gripping force acting on the workpiece to the chuck surface.

When the gripping surfaces of the top jaws contact the workpiece evenly, the mechanical center point of the gripping force is at the center of the gripping surface. If the gripping surfaces contact unevenly or estimation of the gripping center height is difficult, the gripping force should be calculated using the distance from the top jaw top surface to the chuck surface so as to give priority to safety.

- When the gripping center becomes higher, the static gripping force is decreased even if the input force is the same.
- If the gripping center height is higher than, load to be applied to the master jaws, T-nuts, and jaw mounting bolts will increase. To prevent these parts from being damaged, the input force must be reduced to suppress the gripping force to a low level.
- It is recommended to adjust the gripping center height to be H_{max} or less.

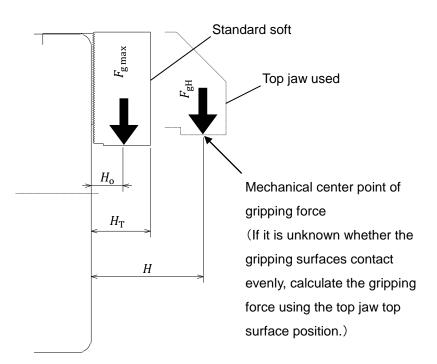


Figure 6 Gripping center height

• *H* when H_{T} is or less

$$F_{\rm gH} = F_{\rm gmax} \times \frac{H_{\rm o} + A}{H + A}$$

H when *H*_T is more than

$$F_{\rm gH} = F_{\rm g\,max} \times \frac{H_{\rm o} + A}{H + A} \times \frac{H_{\rm T} + B}{H + B}$$

3.2.2. Calculation of Loss of Gripping Force due to Centrifugal Force

Centrifugal force is produced on the jaws during chuck rotation. It acts in the direction reducing the gripping force especially in external gripping. This is called "loss of gripping force due to centrifugal force".

Loss of gripping force due to centrifugal force is proportional to the square of the rotational speed, and thorough consideration is necessary especially for high speed rotation. In addition, a larger mass or gravity radius of the top jaws will increase loss of gripping force due to centrifugal force.

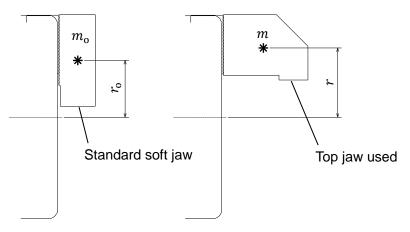


Figure 7 Loss of gripping force due to centrifugal force

• $m \times r$ when $m_o \times r_o$ is more than

$$\Delta F_{\rm c} = z \times (m \times r - m_{\rm o} \times r_{\rm o}) \times \left(\frac{2 \times \pi \times n}{60}\right)^2 \times 10^{-6}$$
$$F_{\rm c} = F_{\rm c \max} \times \frac{n^2}{n_{\rm max}^2} + \Delta F_{\rm c}$$

• $m \times r$ when $m_0 \times r_0$ is or less

$$F_{\rm c} = F_{\rm c\,max} \times \frac{n^2}{n_{\rm max}^2}$$

3.2.3. Determination of Gripping Force

Determine F_{g} in consideration of gripping force loss due to centrifugal force and necessary operating conditions such as cutting conditions, workpiece distortion, and strength of the top jaws. However, F_{g} must be F_{gH} or less. The dynamic gripping force during rotation F_{gD} is calculated as indicated below.

For external gripping

$$F_{\rm gD} = F_{\rm g} - F_{\rm c}$$

• For internal gripping

$$F_{\rm gD} = F_{\rm g} + F_{\rm c}$$

3.2.4. Calculation of Input Force for Operation

Calculate the input force required to obtain the necessary gripping force.

H when *H*_T is or less

$$Q = Q_{\rm max} \times \frac{F_{\rm g}}{F_{\rm gH}}$$

H when *H*_T is more than

$$Q = Q_{\max} \times \frac{F_{g}}{F_{gH}} \times \frac{H_{T} + B}{H + B}$$

3.2.5. Calculation of Hydraulic Pressure in Operation

Calculate the hydraulic pressure to be applied to the rotary hydraulic cylinder to obtain the necessary input force.

The following description is predicated on the use of Kitagawa's SR cylinder or SS-K cylinder. When using another cylinder, refer to its instruction manual.

$$P = (P_{\rm c\,max} - 0.25) \times \frac{Q}{Q_{\rm c\,max}} + 0.25$$

When the hydraulic pressure in operation is less than 0.5 MPa, the cylinder may not operate or the operation speed may become extremely slower.

In this case, it is necessary to increase the input force or select the cylinder again.

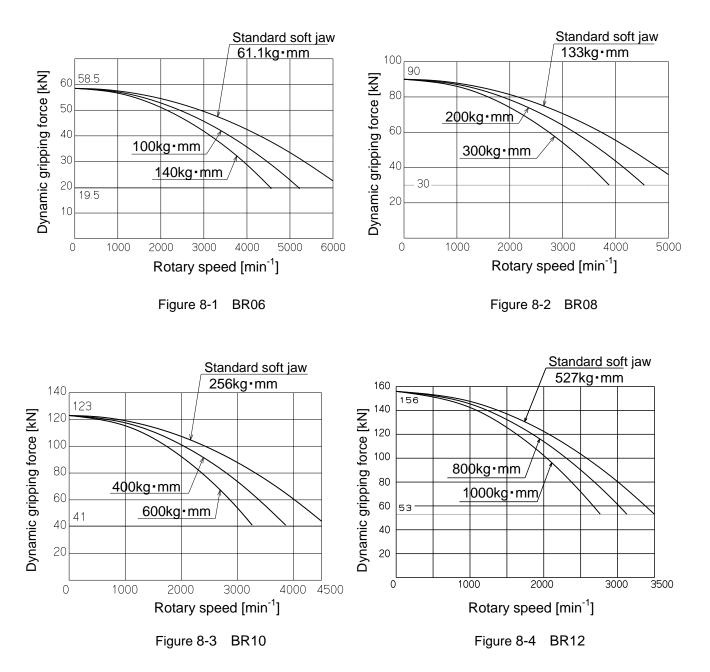
Symbol	Meaning			SR1453	SR1566	SR1781	SR2010
		External gripping	kN	43.9	45	58.7	71.8
Q _{c max}	Max. thrust of cylinder	Internal gripping	kN	47.9	49.7	64.3	75.5
P _{c max}	Max. permissible hydraulic pre	ssure of cylinder	MPa	4.2	4.0	4.0	4.0

Table 6-1 Combination with SR cylinder

Symbol Meaning		SS1453K	SS1666K	SS1881K	SS2110K		
0			kN	52.1	65	73.1	71
Q _{c max}	Max. thrust of cylinder	Internal gripping	kN	56.5	70.6	79.5	74.7
P _{c max}	Max. permissible hydraulic pressure of cylinder MPa		4.5	4.5	4.5	3.5	

3.3. Relationship Between Gripping Force and Rotational Speed

The graphs in Figure 8 indicate the relationship between the gripping force in each moment of mass of the top jaw and the rotational speed. They can be used for approximate calculation of operating conditions.

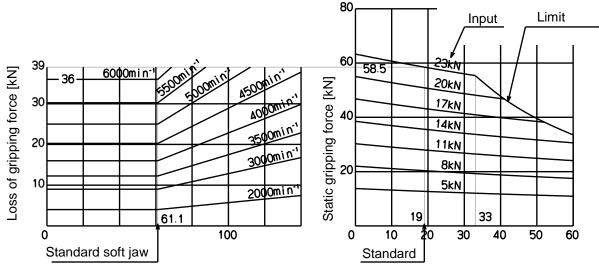


3.4. Relationship Between Gripping Center Height and Static Gripping Force / Input Force Relationship Between Moment of Mass of Top Jaw and Loss of Gripping Force

The graphs in Figure 9 indicate the relationship between the gripping center height and the static gripping force/input force, and the relationship between the moment of mass of the top jaw and the loss of gripping force, respectively. They can be used for approximate calculation of operating conditions.

How to read the graphs is explained below taking BR08 for example.

- When the gripping center height is 21 mm and the input force is 35 kN, the gripping force is 90 kN.
- If the gripping center height exceeds 39 mm, the input force must be reduced. For example, when the gripping center height is 50 mm, the input force is limited to 30 kN or less.
- It is recommended to use the chuck with the gripping center height adjusted to 70 mm or less.
- According to JIS B 6150 : 2015, the loss of gripping force due to centrifugal force must not exceed 2/3 (67%) of the actual static gripping force. Therefore, the permissible loss of gripping force is 60 kN when the static gripping force is 90 kN.
- The loss of gripping force due to centrifugal force is 54 kN when the moment of mass of the top jaw is 133 kg· mm and the rotational speed is 5000 min⁻¹.



The moment of mass of the top jaw 3×m×r [kg·mm]



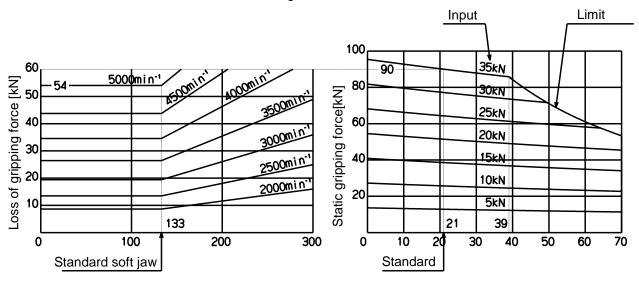


Figure 9-1

BR06

The moment of mass of the top jaw 3×m×r [kg·mm]

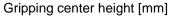
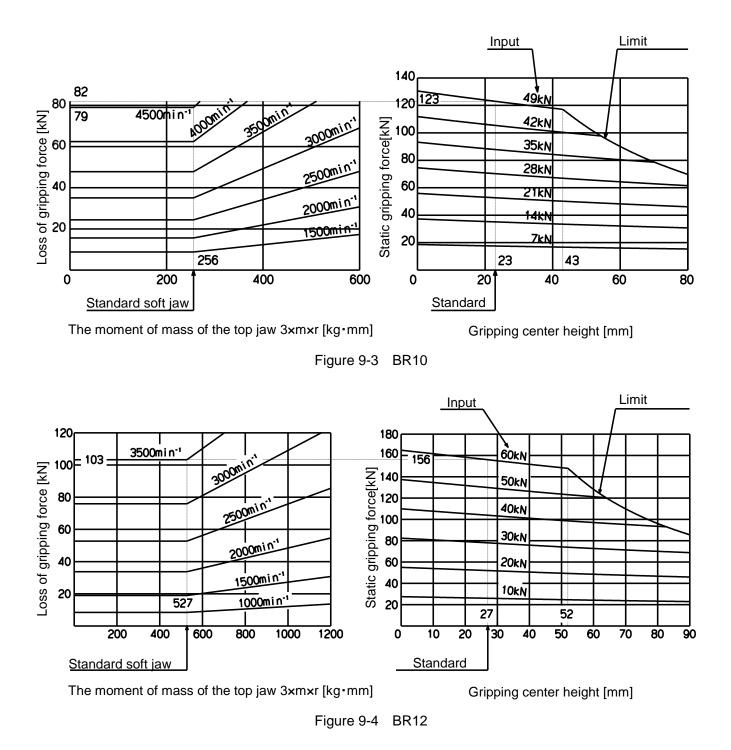


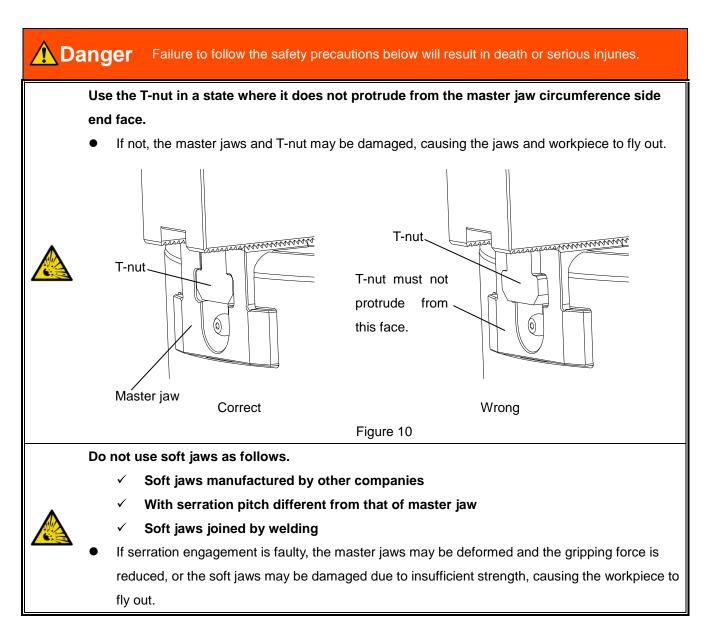
Figure 9-2 BR08

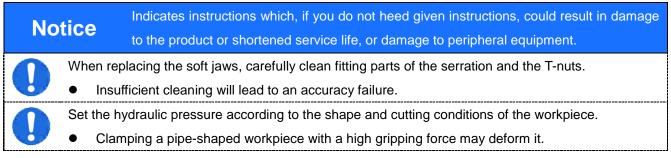


4. Soft Jaw

4.1. Installation of Soft Jaw

The soft jaw mounting positions can be adjusted by loosening the jaw mounting bolts and changing the serration engaging position with the master jaws.





4.2. Stroke mark

A stroke mark to check the jaw stroke position is stamped on the No. 1 jaw part on the body.

When the jaw is at the open end, the base line of the master jaw is aligned with the outer line of the full stroke range as shown in Figure 11.

The base line moves across the full stroke range when the jaw is opened / closed. However, the base line must be within the appropriate stroke range when the chuck grips a workpiece.

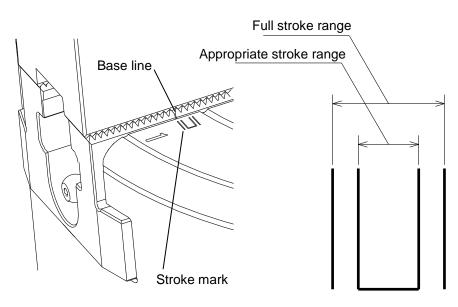


Figure 11 Stroke mark

٦	Гэ	Ы		7
	la	D	e.	1

Туре	BR06	BR08	BR10	BR12
Appropriate stroke range	1	2	2.3	2.7

(mm)

Danger Failure to follow the safety precautions below will result in death or serious injuries.

When gripping a workpiece, the master jaw base line must be within the appropriate stroke range.



- Gripping a workpiece near the stroke end may fail due to unevenness of the tolerance at the workpiece gripping part, causing the workpiece to fly out.
- Frequently gripping a workpiece near the stroke end will apply excessive force to the master jaws and lead to damage of the chuck, causing the workpiece to fly out.

Before starting work, open and close the jaws without gripping a workpiece and confirm that the master jaw base line moves within the full stroke range.

If the jaw stroke becomes insufficient due to chips accumulating inside the chuck or loosened draw nut, the chuck may not grip the workpiece, causing the workpiece to fly out.

4.3. External Gripping Soft Jaw Forming Procedure 1 Preparation of disc for finish turning of top jaw The disc for finish turning of top jaw must have a thickness not to be distorted with the surface roughness of about 25 s. It is convenient to prepare several types of discs with different • \bigcirc θ outside diameters so as to use them properly according to the dimension of the forming part. It is convenient to cut threads at the center in order to guide the disc using a bolt when gripping the disc. 2 Machining of disc gripping part Ą Unclamp the chuck and open the jaws to the maximum. Next, machine D_1 . D_1 must be the dimension that can grip the disc near \Box θ the center of the jaw stroke. $D_1 = d + \frac{\text{jaw stroke}}{2}$ 3 Gripping of disc Grip the disc at the D_1 part. Grip the disc while pressing against the chuck front face to • prevent it from tilting. Stabilize the disc by gripping it several times Confirm that the master jaw base line is within the appropriate • stroke range when the disc is gripped. (Refer to page 21.) (4) Forming Machine D_2 with the disc gripped. D_2 must be the same as the workpiece diameter (approx. H7) and the surface roughness must be 6.3 s or less. 27 θ Set the hydraulic pressure during forming to equal to or slightly • higher than that during machining a workpiece. If the disc becomes deformed, reduce the hydraulic pressure or change the disc shape to the one that is hardly deformed. 5 Test cutting Remove the disc and grip a workpiece. Confirm that the master jaw base line is within the appropriate • stroke range when the workpiece is gripped. (Refer to page 21.) Perform test cutting to confirm that the desired machining • B accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the • gripping surface A and B.

 Preparation of ring for finish turning of top jaw The ring for finish turning of top jaw must have a thickness not to be distorted with the surface roughness of about 25 s. It is convenient to prepare several types of rings with different inside diameters so as to use them properly according to the dimension of the forming part. (2) Machining of ring gripping part Unclamp the chuck and close the jaws to the minimum. Next, machine D₁, D₁ must be the dimension that can grip the disc near the center of the jaw stroke. D₁ = d - jaw stroke (3) Gripping of ring Grip the ring while pressing against the jaws to prevent it from tilting. Stabilize the ring by gripping it several times. Confirm that the master jaw base line is within the appropriate stroke range when the ring is gripped. (Refer to page 21.) (4) Forming Machine D₂ with the ring gripped. D₂ must be the same as the workpiece diameter (approx. H7) and the surface roughness must be 6.3 s or less. Set the hydraulic pressure during forming to equal to or slightly higher than that during machining a workpiece. For internal gripping, use the chuck with 1/2 or less of the max. permissible input force for external gripping. If the ring bacomes deformed, reduce the hydraulic pressure or change the ring and grip a workpiece. Confirm that the master jaw base line is within the appropriate stroke range when the workpiece is gripped. (Refer to page 21.) (5) Test cutting Remove the ring and grip a workpiece. Confirm that the master jaw base line is within the appropriate stroke range when the workpiece is gripped. (Refer to page 21.) Perform test cutting to confirm that the desired machining accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the gripping surface A and B. 	4.4. Internal Suppling Solt Jaw Forming Procedure	
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 Set the hydraulic pressure during forming to equal to or slightly higher than that during machining a workpiece. For internal gripping, use the chuck with 1/2 or less of the max. permissible input force for external gripping. If the ring becomes deformed, reduce the hydraulic pressure or change the ring shape to the one that is hardly deformed. Test cutting Remove the ring and grip a workpiece. Confirm that the master jaw base line is within the appropriate stroke range when the workpiece is gripped. (Refer to page 21.) Perform test cutting to confirm that the desired machining accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the 	D_2 must be the same as the workpiece diameter (approx. H7) and the	
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 stroke range when the workpiece is gripped. (Refer to page 21.) Perform test cutting to confirm that the desired machining accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the 	Remove the ring and grip a workpiece.	
 Perform test cutting to confirm that the desired machining accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the 	• Confirm that the master jaw base line is within the appropriate	
 accuracy is obtained and no slip occurs. Grip the workpiece so that it is brought into contact with the 	stroke range when the workpiece is gripped. (Refer to page 21.)	
Grip the workpiece so that it is brought into contact with the	 Perform test cutting to confirm that the desired machining 	
(A)	accuracy is obtained and no slip occurs.	
gripping surface A and B.	• Grip the workpiece so that it is brought into contact with the	
	gripping surface A and B.	(A)

4.4. Internal Gripping Soft Jaw Forming Procedure

4.5. Tnut-Plus

A Tnut-Plus as shown in Figure 12-1 is provided for BR chucks as an option.

Soft jaws formed using the Tnut-Plus can maintain the gripping accuracy equivalent to just-formed soft jaws even after they are removed from the chuck once, because they can be reinstalled in the same positions.

- For corresponding Tnut-Plus types, refer to Table 4-1.
- To maintain the installation repeatability of the Tnut-Plus for a long period of time, always tighten the jaw mounting bolts from the chuck outside diameter side ① with the specified torque. (See Figure 12-2)
- The Tnut-Plus is elastically deformed when the bolts are tightened. Therefore, the resistance you feel when tightening the bolts is different from ordinary T-nuts, it is normal.
- If the Tnut-Plus is used for a long period of time, the soft jaws may be fixed and become hard to be removed. In this case, remove them by tapping with a plastic hammer. Apply CHUCK GREASE PRO to the side of the T-nut to stop it becoming fixed.
- The gripping accuracy may be deteriorated due to aging such as fatigue of the workpiece gripping surface. In such a case, re-form the soft jaws.

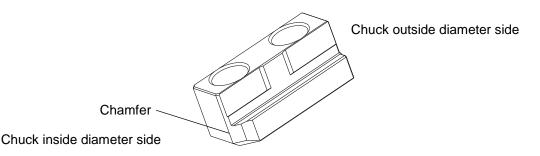


Figure 12-1 Tnut-Plus

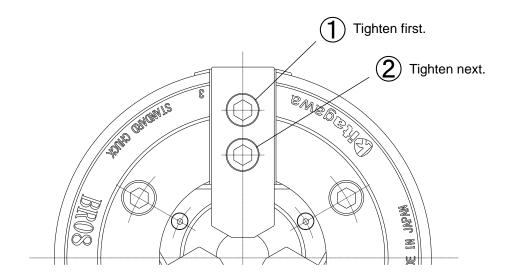


Figure 12-2 Tightening order of the jaw mounting bolts

Warning Failure to follow the safety precautions below could result in death or serious injuries.

Mount the Tnut-Plus with the chamfer side facing the chuck inside diameter side. (See Figure 12-1)

If it is mounted in the opposite direction, seizure may occur due to significant deformation of the master jaws. As a result, the gripping force will be reduced, causing the workpiece to fly out.

Do not use the Tnut-Plus on a chuck that does not correspond to it.

(The T-slot shapes of such chucks do not match the Tnut-Plus, so the Tnut-Plus cannot be mounted physically. Do not use the Tnut-Plus forcedly on such chucks by additionally machining them.)



- If the Tnut-Plus is used on such chucks, seizure may occur due to significant deformation of the master jaws. As a result, the gripping force will be reduced, causing the workpiece to fly out.
- Additional machining of the T-nut and master jaws may damage them, causing the workpiece to fly out.

Do not use soft jaws manufactured by other companies.



- If soft jaws manufactured by other companies are used, seizure may occur due to significant deformation of the master jaws. As a result, the gripping force will be reduced, causing the workpiece to fly out.
- Using soft jaws manufactured by other companies may damage the T-nut, causing the workpiece to fly out.

Notice Indicates instructions which, if you do not heed given instructions, could result in damage to the product or shortened service life, or damage to peripheral equipment.

Do not use soft jaws manufactured by other companies.

When mounting already-formed soft jaws again, use the same T-nut used when the soft jaws were formed, match the jaw No. of the soft jaws and master jaws, and mount the soft jaws in the same

- serration position. Also, carefully clean fitting parts of the serration and the T-nuts.
 - Failure to follow the above precautions may lead to poor accuracy.

5. Additional Machining Allowable Range

When mounting a locator or jig on the body surface, add tapped holes and pin holes within the additional machining allowable range shown by the oblique line parts in Figure 13.

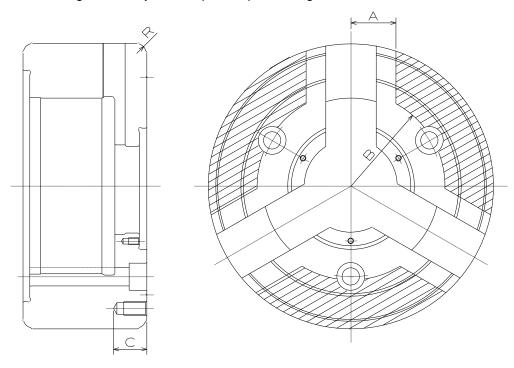


Figure 13 Additional machining allowable range

		Table 8		
Туре	BR06	BR08	BR10	BR12
А	30	33	36	42
В	54.5	69	79.5	94.5
C (max)	25	25	25	30
R	5	7.5	7.5	11.5

(mm)

<u> A</u> Danger

Failure to follow the safety precautions below will result in death or serious injuries.



Provide measures to prevent fly-out by centrifugal force (such as dowel pins) for the locator or jig. In addition, mount the locator or jig with enough bolts with sufficient strength.

• Otherwise, the locator or jig may fly out due to centrifugal force.

6. Maintenance and Inspection

6.1. Periodic Inspection

Interval	Contents
	• Supply grease. When using high speed rotation or a large quantity
	of water soluble coolant, shorten the greasing interval according to
	the operating conditions.
Every day	• Before starting work, open and close the jaws without gripping a
	workpiece and confirm that the master jaw base line moves within
	the full stroke range. (Refer to page 21.)
	• Upon completion of the work, clean the chuck using an air gun.
Every 3 months	Check the bolts of each part for looseness.
Every 6 months or 100,000 strokes	Disassemble and clean the church (Defer to page 22.)
(Cast machining: every 2 months)	• Disassemble and clean the chuck.(Refer to page 28.)

Table 9 Periodic inspection

6.2. Grease Supply

6.2.1. Specified grease

Table 10 Specified grease

Туре	Specified grease	Grease nipple	Grease amount per one point [g]
BR06			4
BR08	CHUCK GREASE PRO	JIS B 1575 : 2000	6
BR10	CHUCK GREASE PRO	type 1 (M6×0.75)	10
BR12			12

6.2.2. Greasing Procedure

- ① Open the jaws, and be sure to turn OFF the main power of the machine before starting the work.
- ② Supply the amount of grease shown in Table 10 from the grease nipple of each master jaw using a grease gun.
- ③ After supplying the grease, open and close the jaws several times without gripping the workpiece.

6.2.3. Safety Information on Grease and Antirust Oil

Applicable range

- Specified grease
- Antirust agent applied to the product at the delivery

For the grease other than the specified one and antirust oil prepared by the customer, refer to the safety data sheet (SDS) prepared for respective oils.

Acrimetica	In case of much aspiration, go to a place where there is fresh air, and cover your	
Aspiration	body with a blanket to keep your body warm. Consult a doctor if necessary.	
Cticking to your skip	Wipe off the oil, and wash your skin with water and soap.	
Sticking to your skin	If you feel itchy or you get inflamed, consult a doctor immediately.	
Entering your eye	Wash your eye with fresh water for at least 15 minutes, and then consult a doctor.	
Accidental drinking Consult a doctor immediately without vomiting forcibly.		

Table 11 First-aid treatment

6.3. Disassembly

Read the following disassembling procedure referring to page 5 and 6.

- ① Before start of work, be sure to turn off the main power of the machine.
- 2 Loosen the jaw mounting bolts [12] and remove the soft jaws [4] and T-nuts [5].
- ③ Loosen the cover mounting bolts [14] and remove the cover [8].
- Loosen the chuck mounting bolts [11] and rotate the draw nut [7] using the draw nut plate wrench [10].
 Then, remove the chuck from the spindle.
- (5) Remove the wedge plunger [2] toward the rear of the chuck.
- 6 Remove the master jaws [3] toward the inner circumference of the chuck.
- Reassemble the product through reverse procedure of disassembly while applying the specified grease sufficiently.
- When reinstalling the chuck to the machine, refer to "8.5 Chuck Installation Procedure".
- After reassembly, it is recommended to confirm that the specified gripping force is obtained according to the procedure on page 12.

Danger Failure to follow the safety precautions below will result in death or serious injuries.



Clean the disassembled parts with kerosene, carefully check them for damage, wear, crack, or seizure, and repair or replace them if necessary.

Continuous use of faulty parts may damage the chuck, causing the workpiece to fly out.

Notice Indicates instructions which, if you do not heed given instructions, could result in damage to the product or shortened service life, or damage to peripheral equipment.

Reassemble the parts with the jaw numbers marked on the body, wedge plunger, and master jaws matched respectively.

Also, do not hit the parts each other or give a shock to them. Be especially careful not to hit the body when installing the master jaw.

• Failure to observe the precautions may result in accuracy failure.

7. Troubleshooting

7.1. Troubleshooting

If a failure is suspected, check the contents in Table 12 again and take necessary measures.

Problem	Cause	12 Troubleshooting Countermeasure
	Parts are damaged	Disassemble and clean the chuck. Replace damaged parts. (Refer to page 28.)
Jaws do not move	Slideways get seized	Disassemble and clean the chuck. Correct the seized part with an oilstone or replace the part. (Refer to page 28.)
	Cylinder does not operate	Check the piping and electric system, and if normal, repair or replace the cylinder.
Stroke is	Chips accumulate inside	Disassemble and clean the chuck. (Refer to page 28.)
insufficient	Draw pipe loosened	Remove the draw pipe from the cylinder and retighten it.
	Jaw stroke insufficient	Confirm that the master jaw base line is within the appropriate stroke range when a workpiece is gripped. (Refer to page 21.)
	Lack of gripping force	Confirm that the hydraulic pressure is appropriate.
Workpiece slips	The formed diameter of the top jaw does not match the workpiece diameter	Re-form the jaw according to the correct forming method. (Refer to "4. Soft Jaw")
	Excessive cutting force	Calculate cutting force and check that it is appropriate for the chuck and machine specifications.
	Lack of grease	Supply grease. (Refer to page 27.)
	Excessive rotational speed	Slow down the rotational speed to obtain required gripping force.
	Swing due to misalignment of the bar feeder, steady rest, tailstock, etc.	Thoroughly conduct alignment to eliminate swing.
	Run-out of chuck circumference is large	Adjust the run-out to 0.020 mm T.I.R. or less.
	Dust accumulates in serration parts of master jaw and top jaw	Remove the top jaws and thoroughly clean the serration parts.
Accuracy failure	Jaw mounting bolts are not sufficiently tightened	Tighten the jaw mounting bolts with the specified torque. (Refer to page 8.)
	Top jaw forming method is improper	Confirm that the disc for finish turning of top jaw is parallel to the chuck end face and it is not deformed by the gripping force.

Table 12 Troubleshooting

Due to excessive top jaw height, top jaws are deformed and jaw mounting bolts are extended	Lower the top jaw height. Adjust the top jaws so that the gripping surfaces contact the workpiece evenly.
Excessive gripping force	Reduce the gripping force to the extent that machining can
deforms workpiece.	be executed to prevent deformation.

7.1.1. Aging of markings due to use

The type and serial numbers marked on the surface of the body may become difficult to see due to prolonged exposure to chips. In such a case, please check the URLs marked on the outer circumference of the body, as they also contain information on the type and serial numbers.

Also, the logo plate (blue K mark) is strongly adhered to the body with adhesive, but for the same reason, it may be scratched or peeled off. If it should peel off, it will not affect performance or safety. This is not a malfunction, so please use the product with peace of mind.

Danger Failure to follow the safety precautions below will result in death or serious injuries. In case that the chuck failed to operate due to a seizure or breakage, remove the chuck from the machine following the disassembly procedure on page 28. When the top jaws and covers cannot be removed due to a blockage of workpiece, do not disassemble forcibly but please contact us or our agent. Forcible disassembly could cause serious human accidents. The chuck must be repaired only by skilled persons who have received the training course.

Repair by unskilled persons or persons other than us or our agents could cause serious human accidents.

7.2. Contact Information In Case Problem Occurs

Please get in touch with our sales agent from which you purchased the chuck or our office of the address given on the back cover when the chuck fails.

For Machine Manufacturers

The sections starting from this page provide explanations for machine manufacturers (who mount the chuck on machines).

Not only machine manufacturers but also persons who attach/detach the chuck are to read and thoroughly understand the contents so as to perform safety work.

8. Installation

8.1. Installation Conceptual Diagram

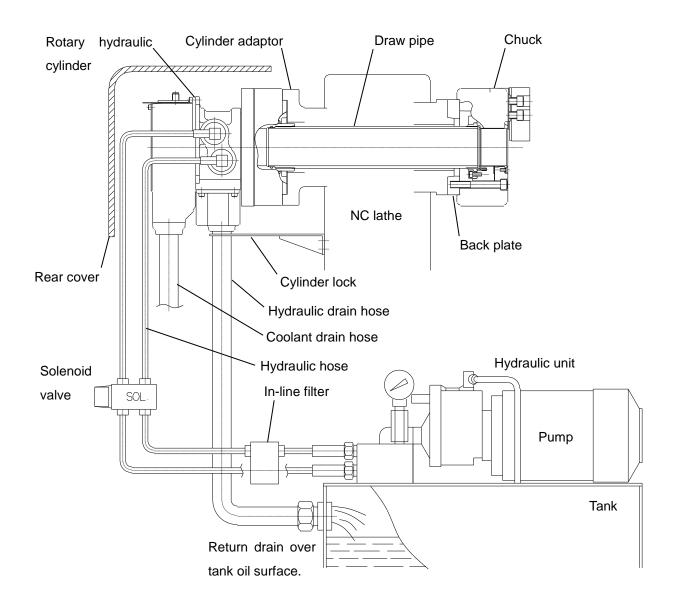


Figure 14 Installation conceptual diagram

▲ Danger Failure to follow the safety precautions below will result in death or serious injuries.



Confirm that the cylinder does not cause pressure drop during machining beforehand when operating other actuators together with the cylinder using the same hydraulic source.



Reduction of hydraulic pressure will reduce the gripping force, causing the workpiece to fly out. Provide the drain hose so that drain flows smoothly without stagnation.

The drain must be returned over the oil surface in the hydraulic unit to prevent back pressure. • If drain does not flow smoothly, the cylinder may cause oil leakage, resulting in fire.



For the cylinder and other peripheral devices, follow their respective instruction manuals.

If not, serious human accidents may occur.

Warning Failure to follow the safety precautions below could result in death or serious injuries.

Eliminate dust in the hydraulic circuit completely. In addition, incorporate an in-line filter.



If foreign substances enter the cylinder, the rotary valve may get seized and the cylinder may rotate while tearing the hose. Moreover, the hydraulic pressure may be blocked, causing the workpiece to fly out.

Use a flexible hose to prevent bending stress and tension from being applied to the cylinder.



If the cylinder is rotated with an external force applied to it, the cylinder rotary valve may get seized and the cylinder may rotate while tearing the hose. Moreover, the hydraulic pressure may be blocked, causing the workpiece to fly out.

Indicates instructions which, if you do not heed given instructions, could result in damage **Notice** to the product or shortened service life, or damage to peripheral equipment.

Especially when using a large hydraulic unit, insert a throttling valve in the pressure supply line to restrict surge pressure.

An excessive surge will shorten the chuck service life.

Use a hydraulic hose with the inside diameter as large as possible and with a piping length as short

as possible.

If the inner diameter is too small or the piping length is too long, the jaw opening/closing speed may become slow.

Provide the drain hose with a slight flow gradient to avoid any air pocket.

If air is mixed in drain, noise caused by the hydraulic unit may increase or the service life of the hydraulic unit may be shorten.

8.2. Back plate

Prepare a back plate corresponding to the spindle end shape and chuck mounting dimensions. The chuck mounting dimensions conform to JIS B 6109-2: 2005.

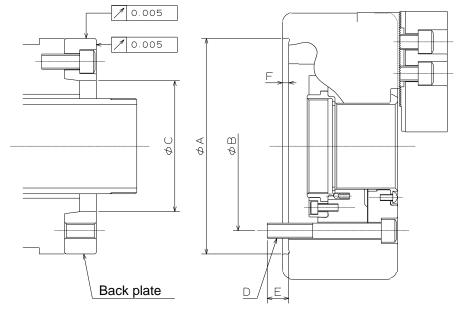
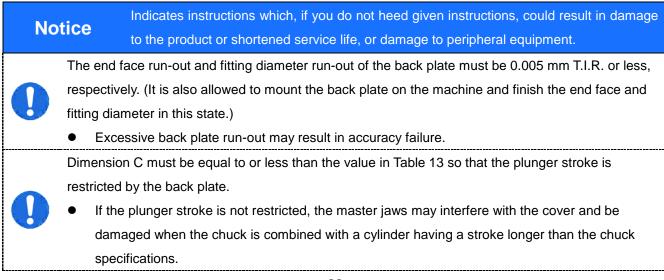


Figure 15 Mounting dimensions

Table 13

Туре	BR06	BR08	BR10	BR12
A (H6)	140	170	220	300
В	104.8	133.4	171.1	235
C (max)	82	104	137	155
D	3×M10	3×M12	3×M16	3×M20
E	16	17	22	29
F	5	5	5	6

(mm)



8.3. Draw Pipe

Determine the draw pipe length L according to the distance X between the chuck mounting face and cylinder mounting face. Whether sufficient strength is obtained with respect to the operating conditions must be judged by the designer of the draw pipe. The dimensions provided in this manual do not guarantee that the draw pipe will not be damaged under every condition.

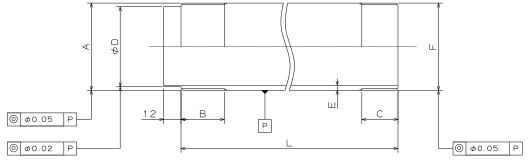


Figure 16 Draw pipe

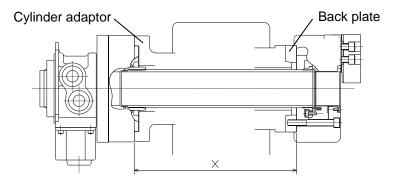


Figure 17 Distance between chuck mounting face and cylinder mounting face

Туре	Cylinder	А	В	С	D (f7)	E (min)	F (max)	L
BR06	SR1453	M60×2	30	20	55	0.5		X+36
DRUO	SS1453K	IVIOUX2	30	20	55	3.5	M60×2	A+30
DDOO	SR1566	MZENO	25	25	70	4 5	MZELLO	V · 44
BR08	SS1666K	M75×2	35	25	70	4.5	M75×2	X+44
DD40	SR1781	Mooura	25	25	05	4.5	MOONO	V . 44
BR10	SS1881K	M90×2	35	25	85	4.5	M90×2	X+41
DD40	SR2010	M4450	25	20	110	4.5	M4450	X : 40
BR12	SS2110K	M115×2	35	30	110	4.5	M115×2	X+40

Table 14Draw pipe dimensions

(mm)



Indicates instructions which, if you do not heed given instructions, could result in damage to the product or shortened service life, or damage to peripheral equipment.

Do not connect Cylinder and Chuck by connecting multiple draw pipes.

Failure to follow the above precautions may lead to poor accuracy.

8.4. Disassembly of Draw Nut and Threading

Read the following procedure referring to page 5 and 6.

- Loosen the plunger mounting bolts [13] and remove the plunger nut [6] and draw nut [7].
 At this time, be careful not to lose the steel ball [15] and coil spring [9].
- ② Cut threads in the draw nut [7] corresponding to the draw pipe thread diameter.
- ③ Assemble the draw nut [7] in the plunger nut [6], and tighten the plunger nut mounting bolts [13].

Danger Failure to follow the safety precautions below will result in death or serious injuries.

Do not cut threads exceeding the dimension F in Table 14 in the draw nut.

The thread accuracy must be 6H / 6g.

If not, the draw nut is damaged due to its insufficient strength and the gripping force is lost instantaneously, causing the workpiece to fly out.

8.5. Chuck Installation Procedure

For the cylinder mounting procedure, also read the instruction manual of the cylinder.

- ① Before start of work, be sure to turn off the main power of the machine.
- ② Apply adhesive to the thread part of the draw pipe and screw the draw pipe in the cylinder piston rod. For the tightening torque to be applied at this time, refer to "2.Important Safety Precautions" on the instruction manual of the cylinder.
- ③ Install the cylinder on the spindle.
- ④ Check the run-out of the cylinder. If normal, connect the hydraulic hose and the drain hose.
- (5) Turn on the machine power, and operate the cylinder several times at 0.5 MPa. If it is normal, <u>move the</u> <u>piston to the forward end</u> and turn off the machine main power.
- 6 Remove the soft jaws and cover of the chuck.
- Insert the draw nut plate wrench into the chuck center hole as shown in figure 18, and connect the draw nut to the draw pipe while rotating the draw nut. If it cannot be screwed in smoothly, do not screw forcibly and check the thread for inclination.
- 8 Rotate the draw nut until the chuck is completely fitted to the spindle installation surface.
- (9) Tighten the chuck mounting bolts evenly with the specified torque. (See "2.Important Safety Precautions") The chuck circumference run-out must be 0.020 mm T.I.R or less. When performing centering adjustment, tap the body side face with a plastic hammer.
- 1 Rotate the draw nut until the master jaw base line is aligned with the outer line of the stroke mark. (Refer to page 21.)

A click stop (locking mechanism) is provided for the draw nut. Finish the adjustment at a position where you feel it click.

① Operate the cylinder at 0.5 MPa and confirm that the master jaw base line moves within the full stroke range. (Refer to page 21.)

If the chuck or cylinder is replaced from another type, calculate and change the hydraulic pressure to obtain the same gripping force as the previous chuck. (Refer to "3.2. Calculation of Operating Condition".)

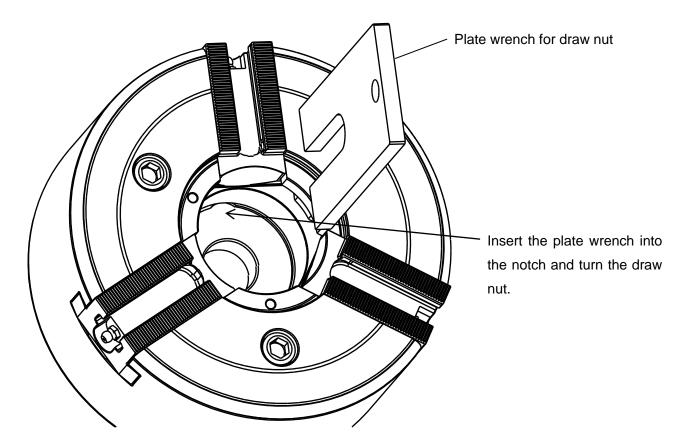


Figure 18

Warning Failure to follow the safety precautions below could result in death or serious injuries.

If the chuck or cylinder is replaced from another type, calculate and change the hydraulic pressure to obtain the same gripping force as the previous chuck. (Refer to "3.2. Calculation



- of Operating Condition".)
 - Insufficient gripping force may cause the workpiece to fly out.
- Especially, when replacing from the BB200 series, it is necessary to increase the oil pressure to obtain the same gripping force as before.

9. Others

9.1. Standard or Directive to Conform

This product conforms to the following EN standards and EU directive:

- Machinery Directive:2006/42/EC Annex I
- EN ISO 12100:2010
- EN1550:1997+A1:2008

9.2. Marking of Product

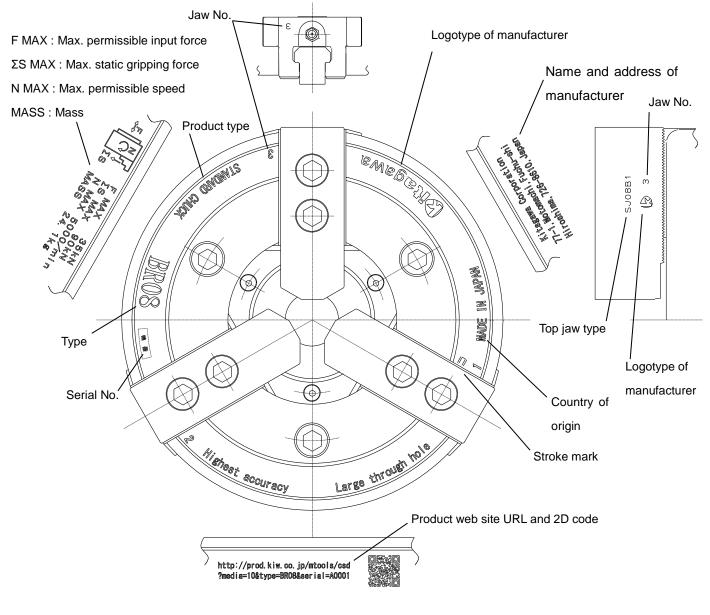


Figure 19 Marking

The mass stamped on the chuck is the value when the standard back plate is included.

Туре	BR06	BR08	BR10	BR12
Back plate	A ₂ -5	A ₂ -6	A ₂ -6	A ₂ -6
Spindle end shape	A2-5	A2-0	A2-0	A2-0
Stamp	13.8 kg	24.1 kg	40.9 kg	76.5 kg

Table 15

9.3. Disposal

Dispose of this unit in accordance with the laws and regulations of your country.



DECLARATION OF INCORPORATION

of partly completed machinery Copy of original

We hereby declare that the following our product conform with the essential health and safety requirements of the EC Machinery Directive so that the product is to be incorporated into end-machinery. The product must not be put into service until end-machinery has been declared in conformity with the provisions of the EC Machinery Directive 2006/42/EC Annex II part 1.A.

We also declare that the specific technical documentation for this partly completed machinery was drawn up according to the EC Machinery Directive 2006/42/EC Annex VII part B.

Product	:	Standard chuck
Model	:	BR series (Models BR06, BR08, BR10, BR12)
Serial number	:	See original declaration
Manufacturer	:	Kitagawa Corporation 77-1, Motomachi, Fuchu-shi, Hiroshima 726-8610, Japan
Authorized compiler in the community	:	Peter Soetebier / Prokurist Kitagawa Europe GmbH Borsigstr.3 D-40880 Ratingen, GERMANY

The essential health and safety requirements in accordance with the EC Machinery Directive 2006/42/EC Annex I were applied and fulfilled: 1.1.2, 1.1.3, 1.1.5, 1.1.6, 1.3.1, 1.3.2, 1.3.4, 1.5.4, 1.5.8, 1.5.9, 1.5.13, 1.6.1, 1.7.1, 1.7.2, 1.7.3, 1.7.4, 1.7.4.1, 1.7.4.2

The following harmonized standards were applied: EN ISO 12100:2010, EN 1550:1997+A1: 2008

Signature	:	See original declaration
Place / Date	:	See original declaration
Name / Title	:	Tomonari Hiromoto / Manager, Technical section 1 Technical department Kitagawa Global hand Company

Being the responsible person appointed and employed the manufacturer.



UK DECLARATION OF INCORPORATION

of partly completed machinery Copy of original

We hereby declare that the following our product conform with the essential health and safety requirements of the Supply of Machinery (Safety) Regulations 2008 so that the product is to be incorporated into end-machinery. The product must not be put into service until end-machinery has been declared in conformity with the provisions of the Supply of Machinery (Safety) Regulations 2008 Annex II part 1.A.

We also declare that the specific technical documentation for this partly completed machinery was drawn up according to the Supply of Machinery (Safety) Regulations 2008 Annex VII part B.

Product	:	Standard chuck
Model	:	BR series (Models BR06, BR08, BR10, BR12)
Serial number	:	See original declaration
Manufacturer	:	Kitagawa Corporation 77-1, Motomachi, Fuchu-shi, Hiroshima 726-8610, Japan
Authorized complier in the community	:	Mark Jones / Financial Director UNIT 1 THE HEADLANS, DOWNTON, SALISBURY, WILTSHIRE, SP5 3JJ, UNITED KINGDOM

The essential health and safety requirements in accordance with the Supply of Machinery (Safety) Regulations 2008 Annex I were applied and fulfilled: 1.1.2, 1.1.3, 1.1.5, 1.1.6, 1.3.1, 1.3.2, 1.3.4, 1.5.4, 1.5.8, 1.5.9, 1.5.13, 1.6.1, 1.7.1, 1.7.2, 1.7.3, 1.7.4, 1.7.4.1, 1.7.4.2

The following harmonized standards were applied: EN ISO 12100:2010, EN 1550:1997+A1: 2008

Signature	:	See original declaration
Place / Date	:	See original declaration
Name / Title	:	Tomonari Hiromoto / Manager, Technical section 1 Technical department Kitagawa Global hand Company

Being the responsible person appointed and employed the manufacturer.



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vitagawa **BR type Standard Chuck** Important



Obtain the Instruction Manual from our website

This document is NOT Instruction Manual. Be sure to download the instruction manual from the following URL or 2D code. Before using this product, be sure to read the instruction manual carefully to understand how to use it correctly. If you need an instruction manual of the booklet, please contact us or the dealer.

https://BRchuck.com





For Machine Manufacturer

Do not ship the product attached to the machine without this document or the instruction manual.

Important Safety Precautions

This document summarizes precautions that particularly you should know or follow. Please read them before starting to use the product.

Failure to follow the safety precautions below will result in death or serious Danger iniuries Turn off the main power supply of the machine when installing, inspecting, greasing, or

replacing the chuck.

The chuck may rotate unexpectedly and entangle your body or clothing.

Do not rotate the spindle with the door open.

Provide an interlock to allow spindle rotation only when the door is closed.

If the door is not closed, the rotating chuck may entangle your body or clothing or cause the workpiece to fly out.

Do not turn OFF the hydraulic pump or operate the solenoid valve during spindle rotation. Before performing workpiece transfer during spindle rotation on an opposed 2-spindle lathe, confirm the machine manufacturer that the operation can be performed safely.

Operating the solenoid valve during spindle rotation will drop or block the hydraulic pressure, causing the gripping force to drop suddenly and the workpiece to fly out.

The rotational speed and input force must not exceed the limit in operation.

Excessive rotational speed may cause the workpiece to fly out.

Excessive input force may damage the chuck, causing the workpiece to fly out.

Only the machine manufacturer or the user is to determine cutting conditions, gripping force, and rotational speed according to test cutting result. Adjust the hydraulic pressure so as to obtain the gripping force necessary for machining, and confirm that the necessary gripping force is obtained before starting machining.

Insufficient gripping force may cause the workpiece to fly out.

If you use a top jaw higher or heavier than the standard top jaw, determine the operating

condition according to "3.2. Calculation of Operating Condition" on the instruction manual. Using a top jaw under excessive operating conditions may damage the chuck, causing the workpiece to fly out.

For internal gripping, use the chuck with 1/2 or less of the max. permissible input force for external gripping.

Excessive input force may damage the chuck, causing the workpiece to fly out.

When using fixed jaws instead of one or two top jaws, the input force must be 2/3 or less or 1/3 or less of the max. permissible input force.

Since the input force that is normally applied to three jaws evenly is concentrated in two or one jaw, the chuck may be damaged, causing the workpiece to fly out.

The gripping diameter must be equal to or less than the body outside diameter.

Using the chuck with the gripping diameter exceeding the body outside diameter may damage the chuck, causing the workpiece to fly out.

When machining a workpiece with a long protrusion, support it with the steady rest or the tailstock.

If not, the workpiece may turn at the end, causing the workpiece to fly out.

Do not grip a workpiece with slope shapes or tapered shapes such as a cast. Otherwise, the workpiece may slip, causing it to fly out.

If a workpiece or jig causes an unbalance, reduce the rotational speed or correct the state by mounting a balance weight. The recommended balance quality is G6.3 or less in JIS B 0905:1992.

An unbalanced workpiece generates centrifugal force, causing the workpiece to fly out.

Vibration generated by the unbalance may damage the chuck, causing the workpiece to fly out. Confirm that the chuck or workpiece does not interfere with the cutter or the turret at a low rotational speed before starting machining.

A large impact on the chuck or workpiece by interference may damage the chuck, causing the chuck or workpiece to fly out.

If an impact is given to the machine by interference between the chuck/workpiece and the cutter/turret due to malfunction or program errors, immediately stop rotation. Then thoroughly check for damage or crack on the parts by disassembling and cleaning them and perform repair or replacement if necessary.

The impact may cause damage or crack on the parts. Continuous use of faulty parts may damage the chuck, causing the workpiece to fly out.

Use the chuck and cylinder that are both manufactured by Kitagawa.

If you must use the chuck together with a cylinder manufactured by another company, confirm

Kitagawa or sales agents that the combination of the chuck and the cylinder is safe.

Depending on the combination with a particular cylinder, the chuck and the cylinder may be damaged, causing the workpiece to fly out.

Be sure to tighten the bolts with the specified torgue listed in Table.

Use a proper tool that can control torque such as a torque wrench.

Use only the bolts attached to the chuck. Do not use other bolts.

Rotating the chuck with the jaw mounting bolts loosened may cause the jaws and workpiece to fly out. If insufficient bolts are mounted, bolt length is wrong, or tightening torque is improper, the bolts may be damaged, causing the chuck and workpiece to fly out.

Specified torque for hex. socket head cap screw

Thread size	M5	M6	M8	M10	M12	M14	M16	M20	M22	M24
Tightening torque [N•m]	7.5	13	33	73	107	171	250	402	539	666
* Strength classification: M20 or smaller = 12.9, M22 or larger = 10.9										

Specified torque for hex, socket button head screw

Specified for the source button head screw								
Thread size	M3	M4	M5	M6	M8	M10	M12	M16
Tightening torque [N•m]	1.4	3.2	6.4	10.8	26.3	52.1	90.9	224

Prevent your hands and fingers from being caught when gripping a workpiece with the chuck. Otherwise, your hands and fingers may be crushed or cut off.

If any of the abnormalities shown below suddenly occurs during operation, it may be a sign of damage of the chuck.

- ✓ The workpiece slips.
- ✓ Chuck gripping force is reduced.

- ✓ Chattering occurs.
- Machining accuracy has become worse.
 Machine vibration has been increased.

(Gripping force is not increased even by increasing hydraulic pressure.)

If the status is not improved even after taking the measures described, immediately stop using the chuck.

Continuous use of faulty parts may damage the chuck, causing the workpiece to fly out.

If the cylinder combined is to be changed due to such as model change of a rotary hydraulic cylinder, change the hydraulic pressure accordingly so as to obtain proper gripping force. Use of the chuck under low hydraulic pressure leads to insufficient gripping force, causing the workpiece to fly out. Use of the chuck under high hydraulic pressure leads to damage of the chuck,

causing the workpiece to fly out. The draw pipe must have sufficient strength with respect to the operating conditions, not

causing run-out and unbalance. The thread accuracy must be 6H / 6g. Tighten the thread securely with a sufficient penetration length.

causing the workpiece to fly out. Use a stroke control sensor built-in type cylinder.



specified grease.

workpiece to fly out.

Туре	Specified gro
BR06	
BR08	
BR10	CHUCK GREAS
BR12	

Remove the eye bolts and wrench from the chuck after use

Use rustproof coolant.

Use the attached standard T-nut for BR12.

If use the T-nut that has C0.2 chamfer, seizure may occur due to significant deformation of the master jaws. As a result, the gripping force will be reduced, causing the workpiece to fly out.



	Caution	Failure
<u> </u>	Caution	injuries

Do not touch machined workpieces with bare hands.

floor-operated crane.

Lifting a heavy chuck by hands will cause a backache

Insufficient strength of the draw pipe, vibration due to unbalance, and looseness of the thread may damage the draw pipe. If the draw pipe is broken, the gripping force is lost instantaneously,

Use a lock valve (check valve) built-in type cylinder. Design the hydraulic circuit so that the solenoid valve holds the gripping port position when the current is not applied.

Sudden drop or interruption of hydraulic pressure due to power failure or hydraulic pump failure will lose the gripping force instantaneously, causing the workpiece to fly out.

If the jaw stroke becomes insufficient due to chips accumulating inside the chuck or loosened draw nut, the chuck may not grip the workpiece, causing the workpiece to fly out.

Failure to follow the safety precautions below could result in death or serious

Perform additional machining of tapped holes and pin holes on the chuck only within the allowable range. Additional machining performed out of the allowable range may damage the chuck, causing the workpiece to fly out. Especially, additional machining to the master jaws and T-nut directly causes fly-out of the workpiece.

Supply grease every day. When supplying grease, turn OFF the machine main power and be sure to use the

Insufficient greasing or use of grease other than the specified one may drop the gripping force, causing the

	Specified grease	
ease	Grease nipple	Grease amount per one point [g]
SE PRO		4
	JIS B 1575 : 2000	6
	type 1 (M6×0.75)	10
		12

Disassemble and clean the chuck every six months or 100,000 strokes (cast machining: every two months). Omitting the disassembly and cleaning and use of the chuck with chips and coolant remaining inside the chuck will lead to insufficient stroke and gripping force drop, causing the workpiece to fly out.

Rotating the chuck without removing the eye bolts and wrench may cause them to fly out.

Otherwise, rust that will be formed inside the chuck may drop the gripping force, causing the workpiece to fly out.

When stopping the machine for a long time or when storing the chuck without using it for a long period, supply grease and rustproof them beforehand.

Otherwise, rust that will be formed inside the chuck may drop the gripping force, causing the workpiece to fly out. Do not wear clothing or accessories such as gloves and necktie which are easy to be caught in.

Otherwise, your body or clothing may be entangled

Do not perform the work after drinking alcohol or taking medicine.

Impaired judgment or operation mistake may cause serious hazards.

When using T-nut of BB212, measure the chamfer dimensions below, and do not use C0.2 T-nut .



to follow the safety precautions below may result in minor or moderate

Touching workpieces with bare hands may cause a burn because the workpieces may be very hot.

Remove the workpiece from the chuck when stopping the machine for a long time.

Failure to do so may lead to drop or interruption of hydraulic pressure or malfunction of the cylinder, causing the workpiece to drop.

When attaching/detaching the chuck to/from the machine, use appropriate lifting devices such as eve bolts and a

Slipping and dropping the chuck from hands may result in a bruise.